

Code: EC4T1

**II B.Tech - II Semester – Regular Examinations - JUNE 2014**

**CONTROL SYSTEMS  
(ELECTRONICS AND COMMUNICATION  
ENGINEERING)**

Duration: 3 hours

Marks: 5x14=70

Answer any FIVE questions. All questions carry equal marks

- 1. a) Define the terms
  - (i) Transfer function
  - (ii) Impulse Response. 5 M
  
- b) Write the differences between Open Loop and Closed Loop systems. 5 M
  
- c) Discuss the advantages of the negative feedback control systems. 4 M
  
- 2. a) Find the transfer function of the following block diagram shown in Figure 1. 10 M

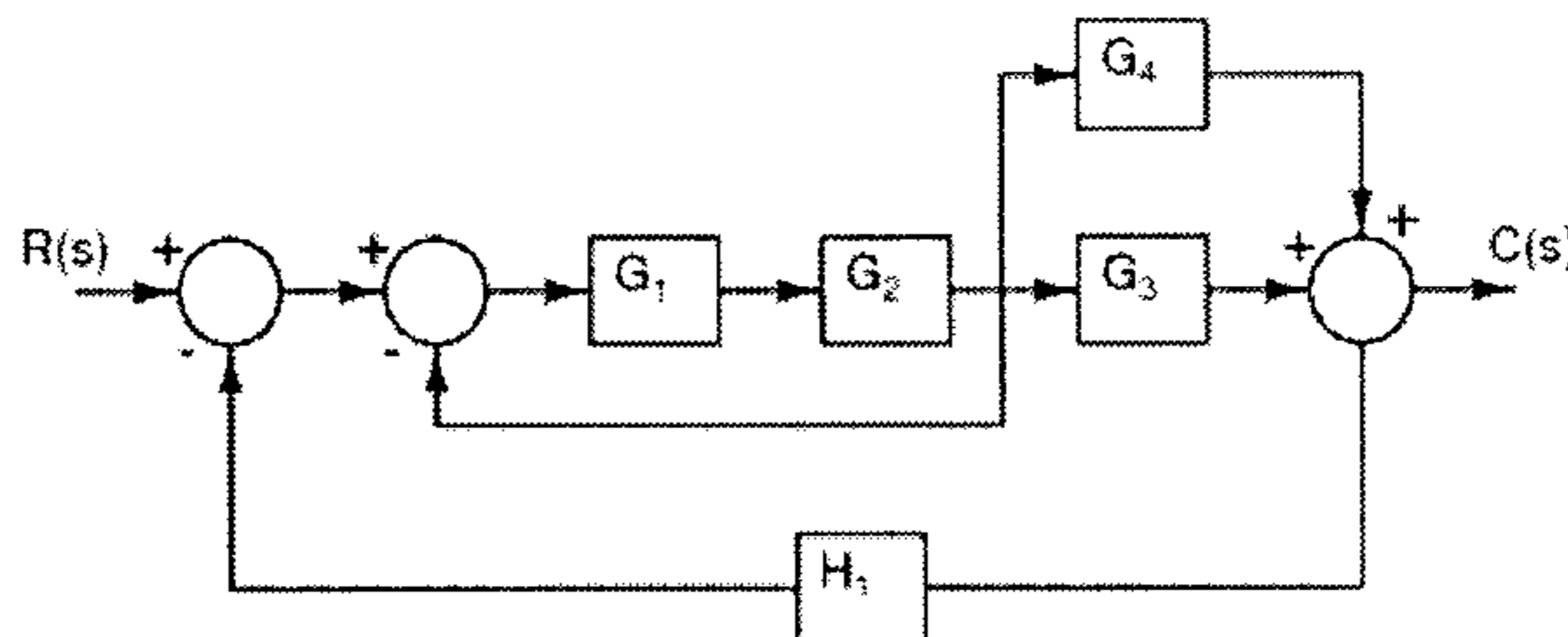


Figure 1

b) Draw the signal flow graph of the above block diagram shown Figure 1. 4 M

3. A unit step input is applied to a Second order Closed loop System whose Closed Loop Transfer function is

$$\frac{C(s)}{R(s)} = \frac{\omega_n^2}{s^2 + 2\xi\omega_n s + \omega_n^2}$$

where  $\xi = 0.8$  and  $\omega_n = 5$  rad/sec then find

- |                      |                    |      |
|----------------------|--------------------|------|
| (i) Rise Time        | (ii) Peak Time     |      |
| (iii) Peak Overshoot | (iv) Settling Time | 14 M |

4. a) A unity feedback control system has an open loop transfer

Function 
$$G(s) = \frac{K}{s(s+4)(s+10)}$$

Sketch the root locus plot of the system indicating the following

- |                                       |     |
|---------------------------------------|-----|
| (i) Centroid and angles of asymptotes |     |
| (ii) Breakaway points                 | 9 M |

b) Find the range of 'K' in order to have the above system to be stable. 5 M

5. Sketch the Bode plot for the given open loop transfer function

$$G(s) = \frac{100}{s(1+0.1s)(1+0.01s)}$$

then find (i) Gain Margin (ii) Phase Margin 14 M

6. a) Using Nyquist criterion determine whether the closed loop systems having an open loop transfer function is stable or not

$$G(s)H(s) = \frac{180}{(s+1)(s+2)(s+5)} \quad 9 \text{ M}$$

- b) Draw the polar plot of open loop transfer function

$$G(s) = \frac{1}{s^2} \quad 5 \text{ M}$$

7. a) What is the effect of proportional derivative controller on stability of a system, Explain it with an example. 7 M

- b) Discuss about Lag compensator and Lead Compensator and show their pole zero locations. 7 M

8. a) Determine the State model of a system which has the following governing differential equation

$$\frac{d^2x}{dt^2} + 5x + 4 = 5u(t) \quad 7 \text{ M}$$

- b) List out the properties of State transition matrix. 7 M